

Advanced Topics in AI

Solving CSPs



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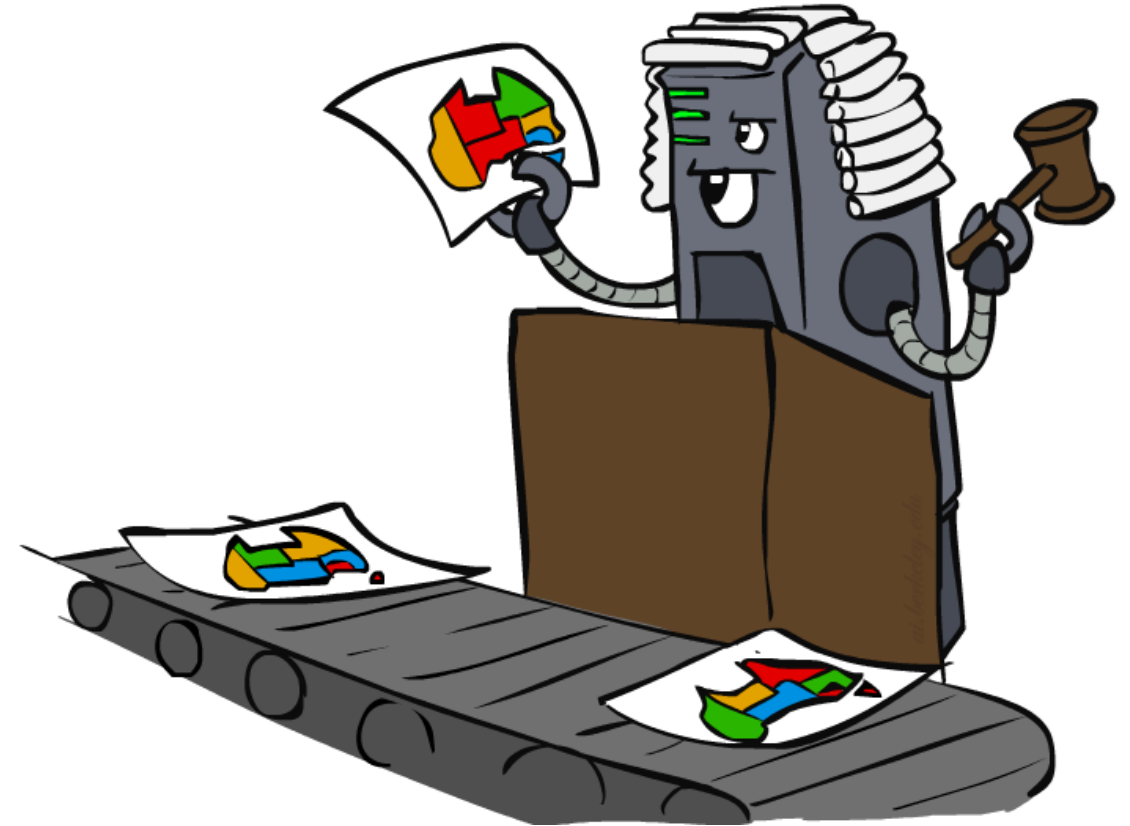
[These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley. All materials are available at <http://ai.berkeley.edu>.]



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Standard Search Formulation

- Standard search formulation of CSPs
- States defined by the values assigned so far (partial assignments)
 - **Initial state:** the empty assignment, $\{\}$
 - **Successor function:** assign a value to an unassigned variable
 - **Goal test:** the current assignment is complete and satisfies all constraints
- We'll start with the straightforward, naïve approach, then improve it

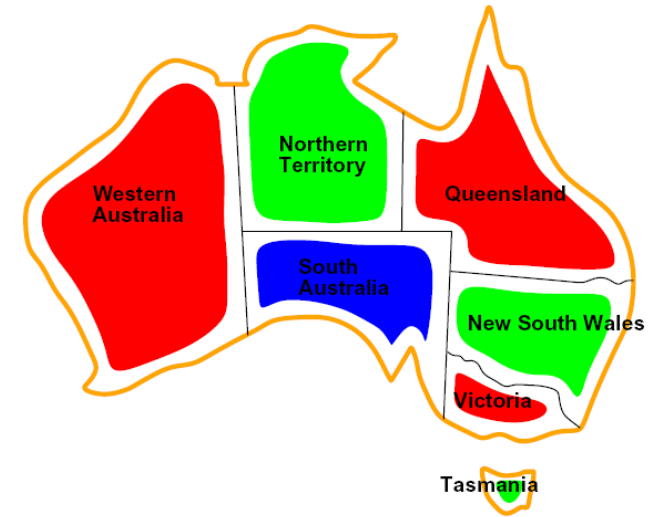


Search Methods

- What would BFS do?

}

{WA = g} {WA = r} ... {NT = g} ...

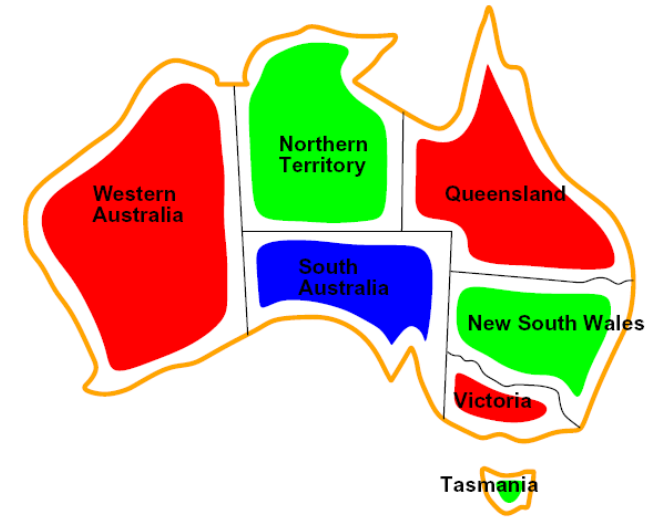


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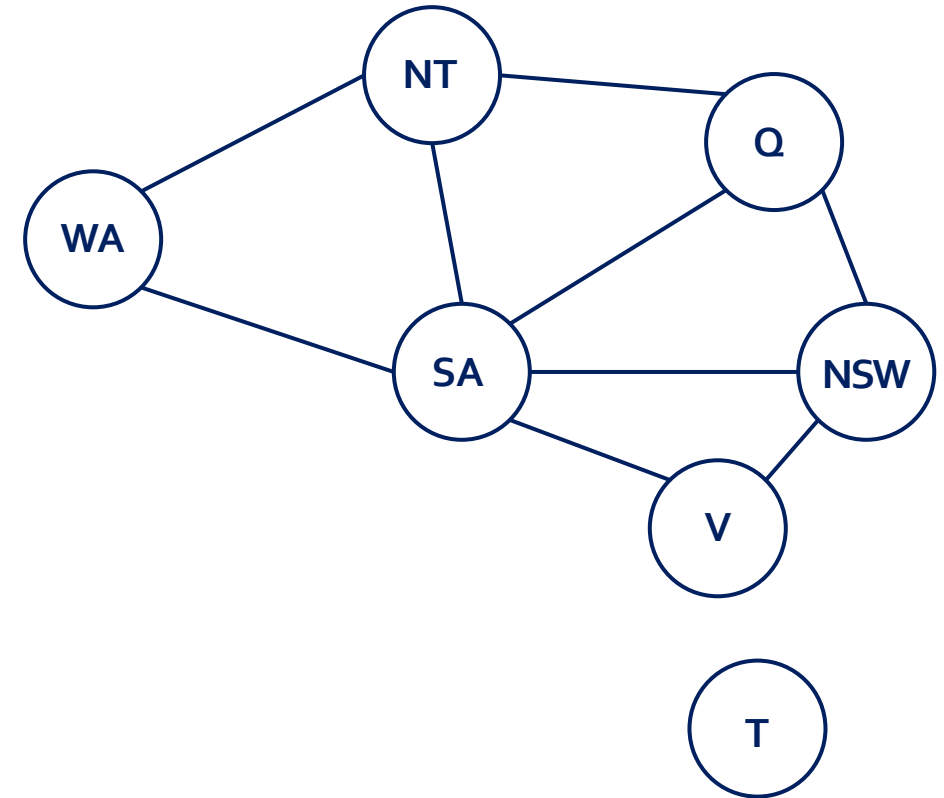
Search Methods

- What would BFS do?
- What would DFS do?
 - let's see!
- What problems does naïve search have?



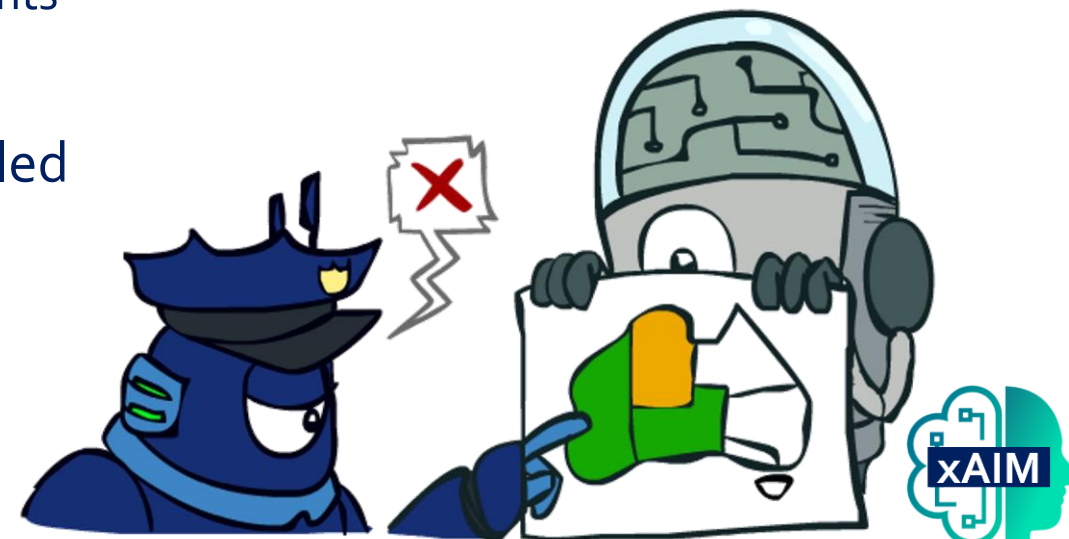
Search Methods

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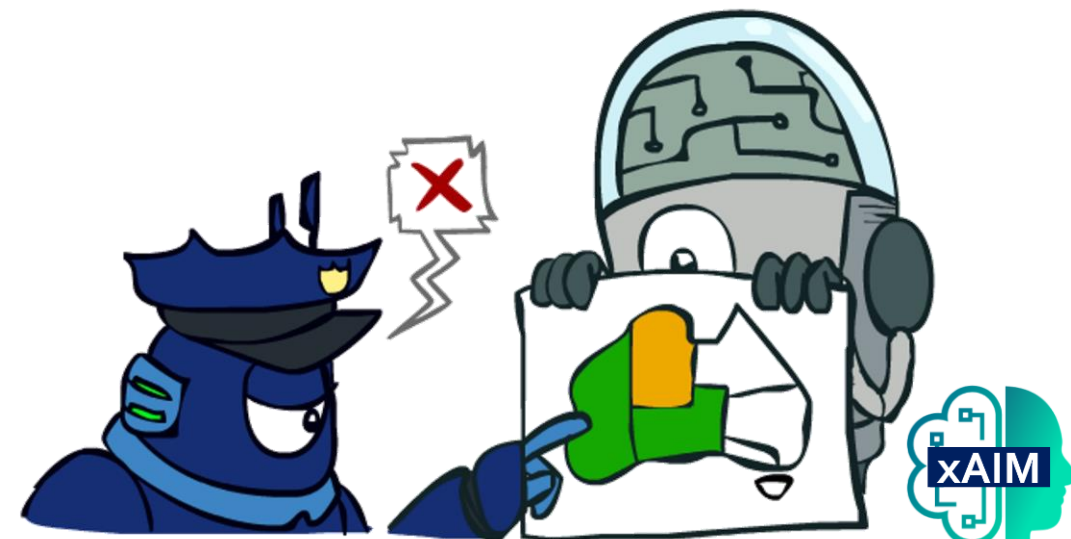
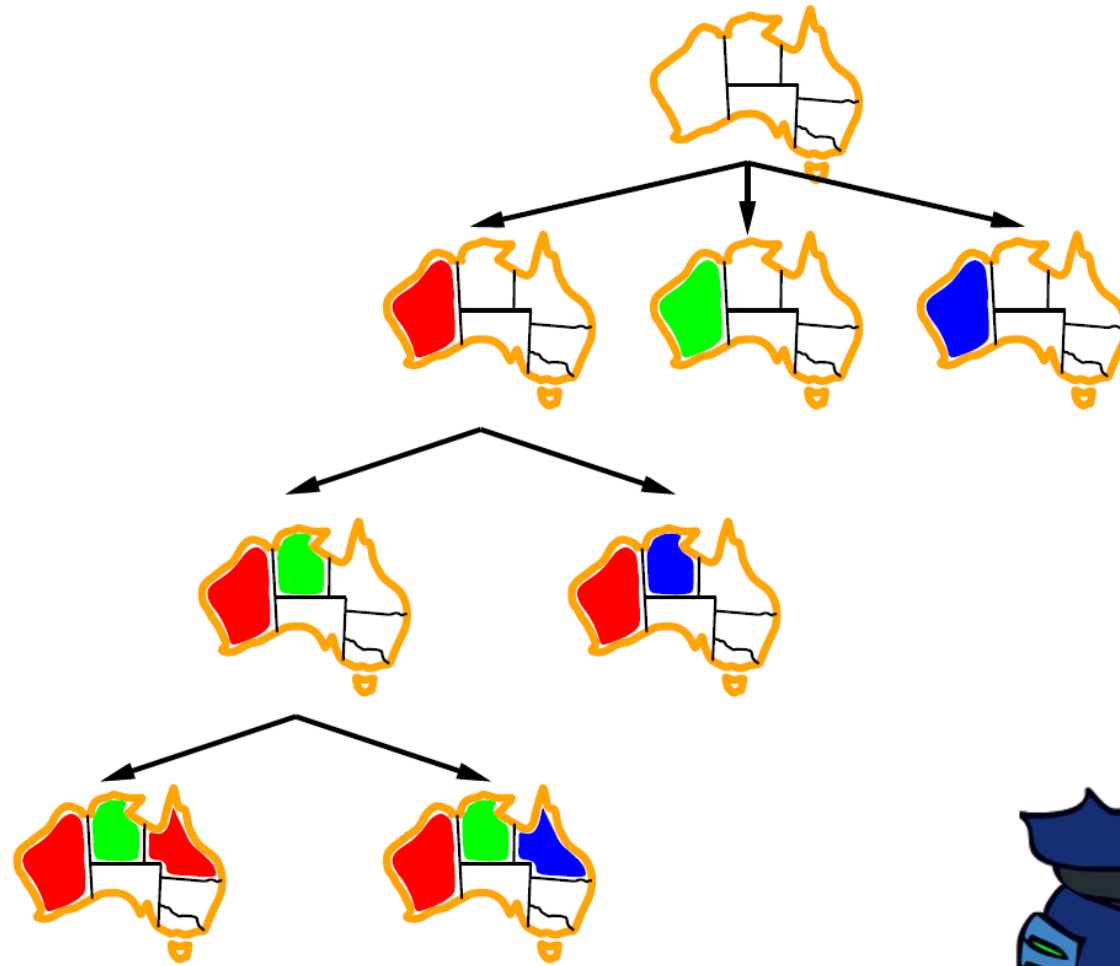


Backtracking Search

- Backtracking search is the basic uninformed algorithm for solving CSPs
- Idea 1: One variable at a time
 - Variable assignments are commutative, so fix ordering
 - I.e., [WA = red then NT = green] same as [NT = green then WA = red]
 - Only need to consider assignments to a single variable at each step
- Idea 2: Check constraints as you go
 - I.e. consider only values which do not conflict with previous assignments
 - Might have to do some computation to check the constraints
 - “Incremental goal test”
- Depth-first search with these two improvements is called *backtracking search* (not the best name)
- Can solve n-queens for $n \approx 25$



Backtracking Example



Backtracking Search

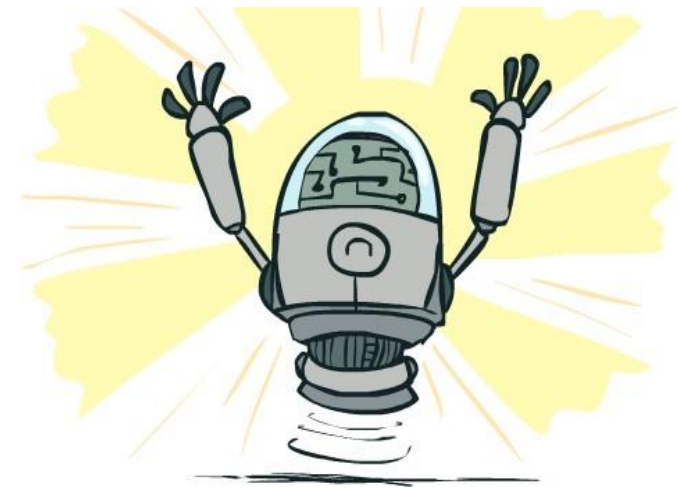
```
function BACKTRACKING-SEARCH(csp) returns a solution, or a failure  
  return RECURSIVE-BACKTRACKING({}, csp)
```

```
function RECURSIVE-BACKTRACKING(assignment, csp) returns soln or failure  
  if assignment is complete then return assignment  
  var ← SELECT-UNASSIGNED-VARIABLE(VARIABLES[csp], assignment, csp)  
  for each value in ORDER-DOMAIN-VALUES(var, assignment, csp), do  
    if value is consistent with assignment given CONSTRAINTS[csp] then  
      add {var = value} to assignment  
      result ← RECURSIVE-BACKTRACKING(assignment, csp)  
      if result ≠ failure then return result  
      remove {var = value} from assignment  
  return failure
```

- Backtracking = DFS + variable-ordering + fail-on-violation
- What are the choice points?

Improving Backtracking

- General-purpose ideas give huge gains in speed
- Ordering:
 - Which variable should be assigned next?
 - In what order should its values be tried?
- Filtering: Can we detect inevitable failure early?
- Structure: Can we exploit the problem structure?



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Next: Filtering



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