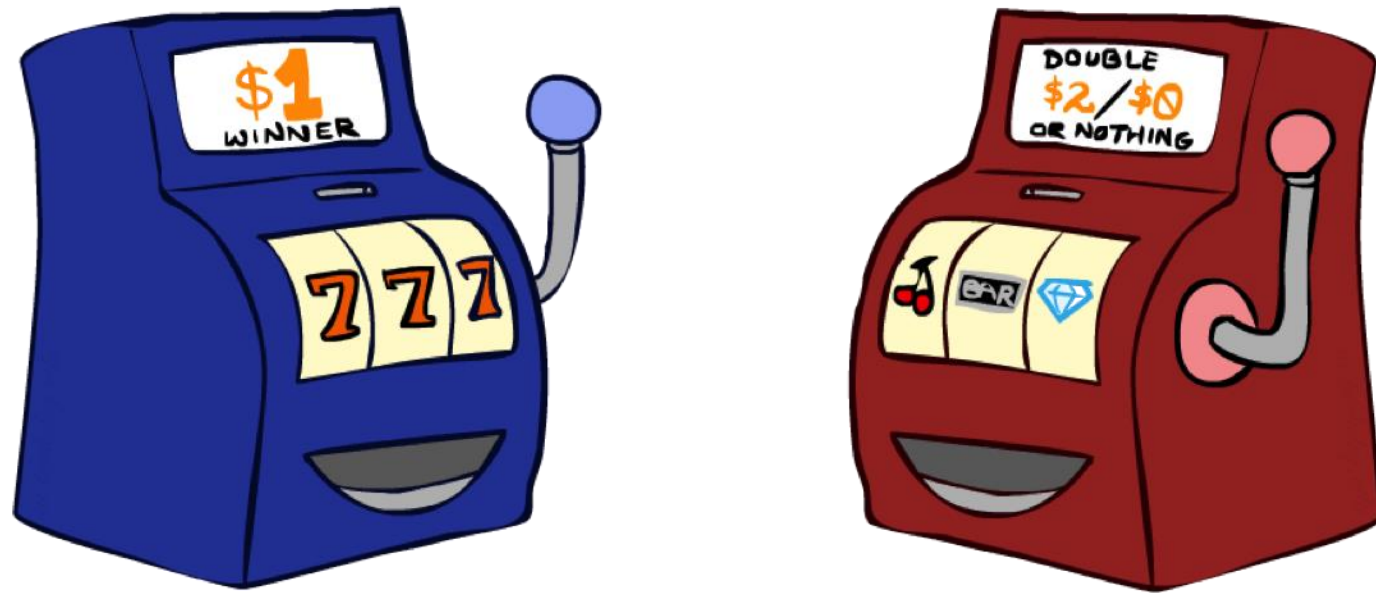


# Advanced Topics in AI

## Summary and Outlook



Instructor: Prof. Dr. techn. Wolfgang Nejdl

Leibniz University Hannover

[These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley. All materials are available at <http://ai.berkeley.edu>.]

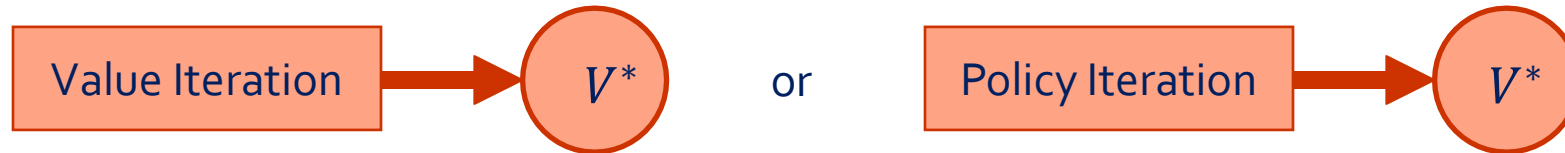


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# Summary: MDP Algorithms

- So you want to....

- Compute optimal values: use value iteration or policy iteration



- Compute values for a particular policy: use policy evaluation



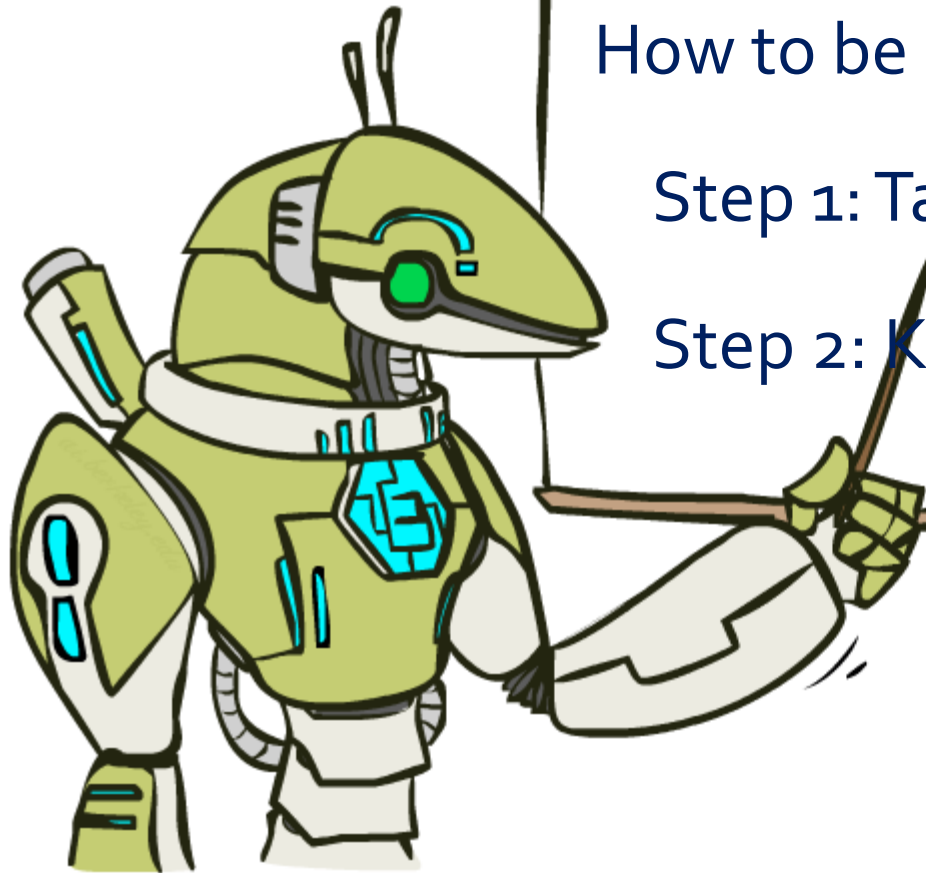
- Turn your values into a policy: use policy extraction (one-step lookahead)



# Summary: MDP Algorithms

- So you want to....
  - Compute optimal values: use value iteration or policy iteration
  - Compute values for a particular policy: use policy evaluation
  - Turn your values into a policy: use policy extraction (one-step lookahead)
- These all look the same!
  - They basically are – they are all variations of Bellman updates
  - They all use one-step lookahead expectimax fragments
  - They differ only in whether we plug in a fixed policy or max over actions

# The Bellman Equations

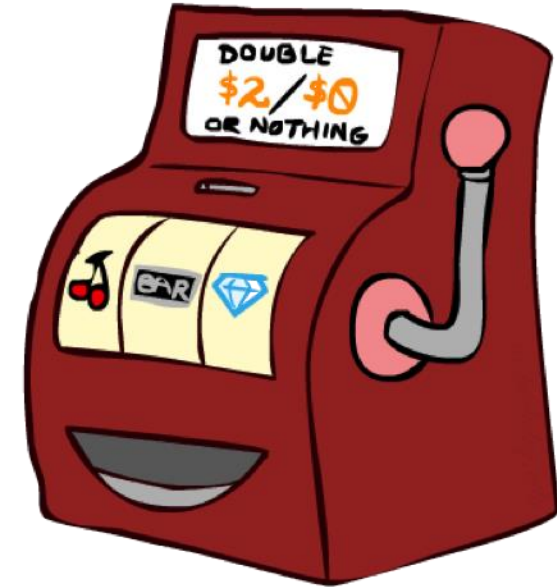
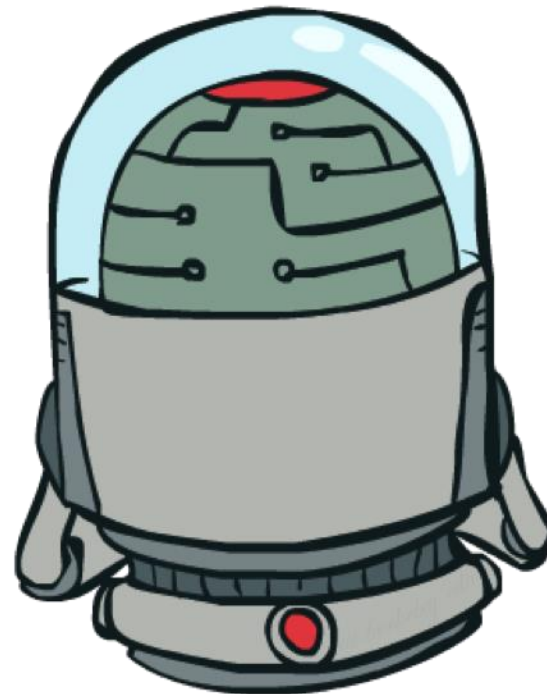


How to be optimal:

Step 1: Take correct first action

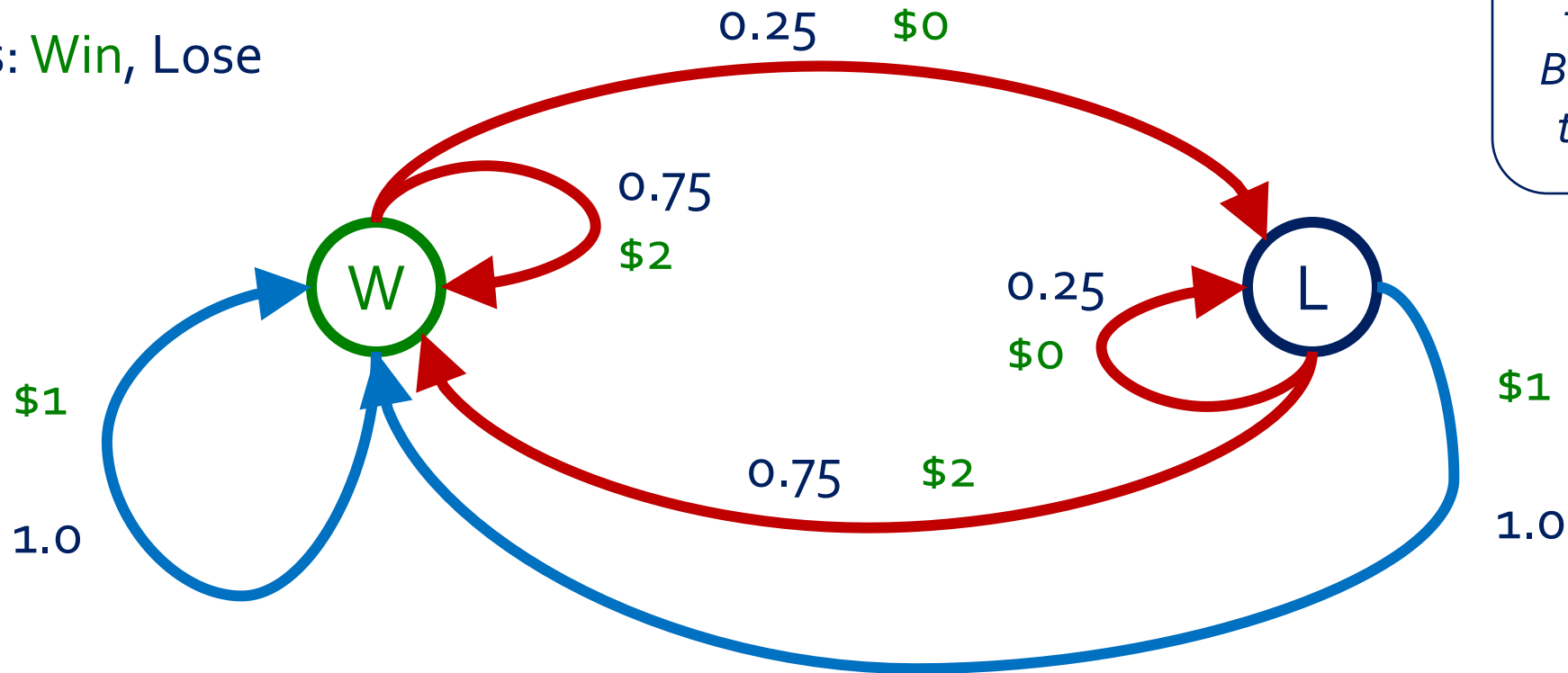
Step 2: Keep being optimal

# Double Bandits



# Double-Bandit MDP

- Actions: *Blue, Red*
- States: *Win, Lose*



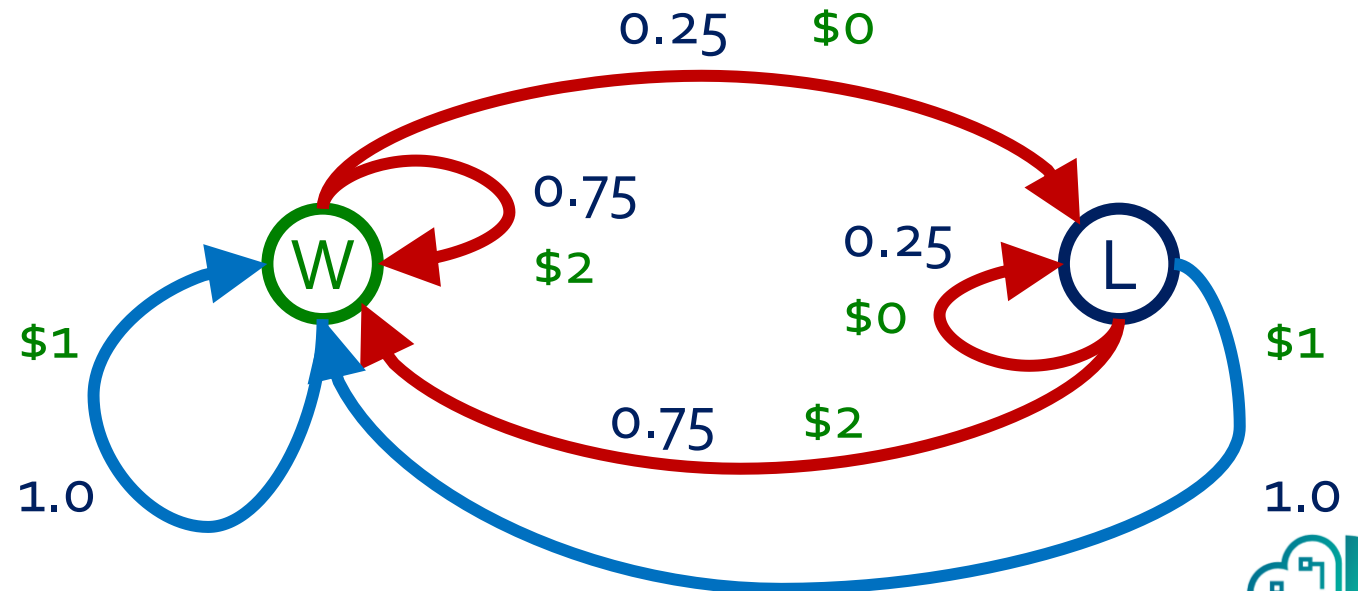
*No discount  
100 time steps  
Both states have  
the same value*

# Offline Planning

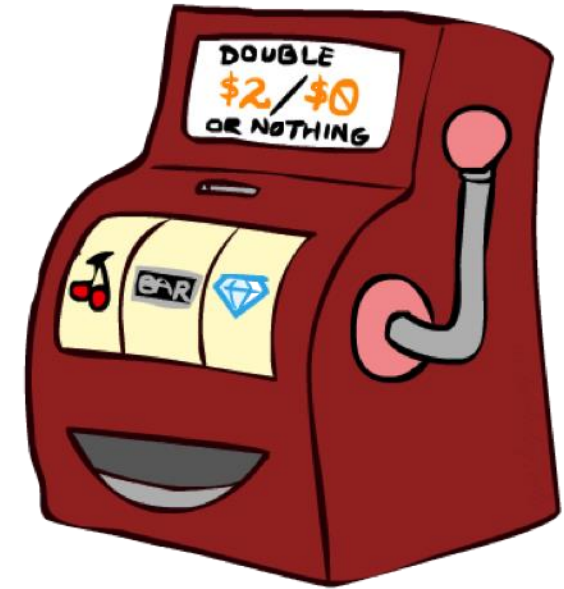
- Solving MDPs is offline planning
  - You determine all quantities through computation
  - You need to know the details of the MDP
  - You do not actually play the game!

*No discount  
100 time steps  
Both states have  
the same value*

	Value
Play Red	150
Play Blue	100



# Let's Play!



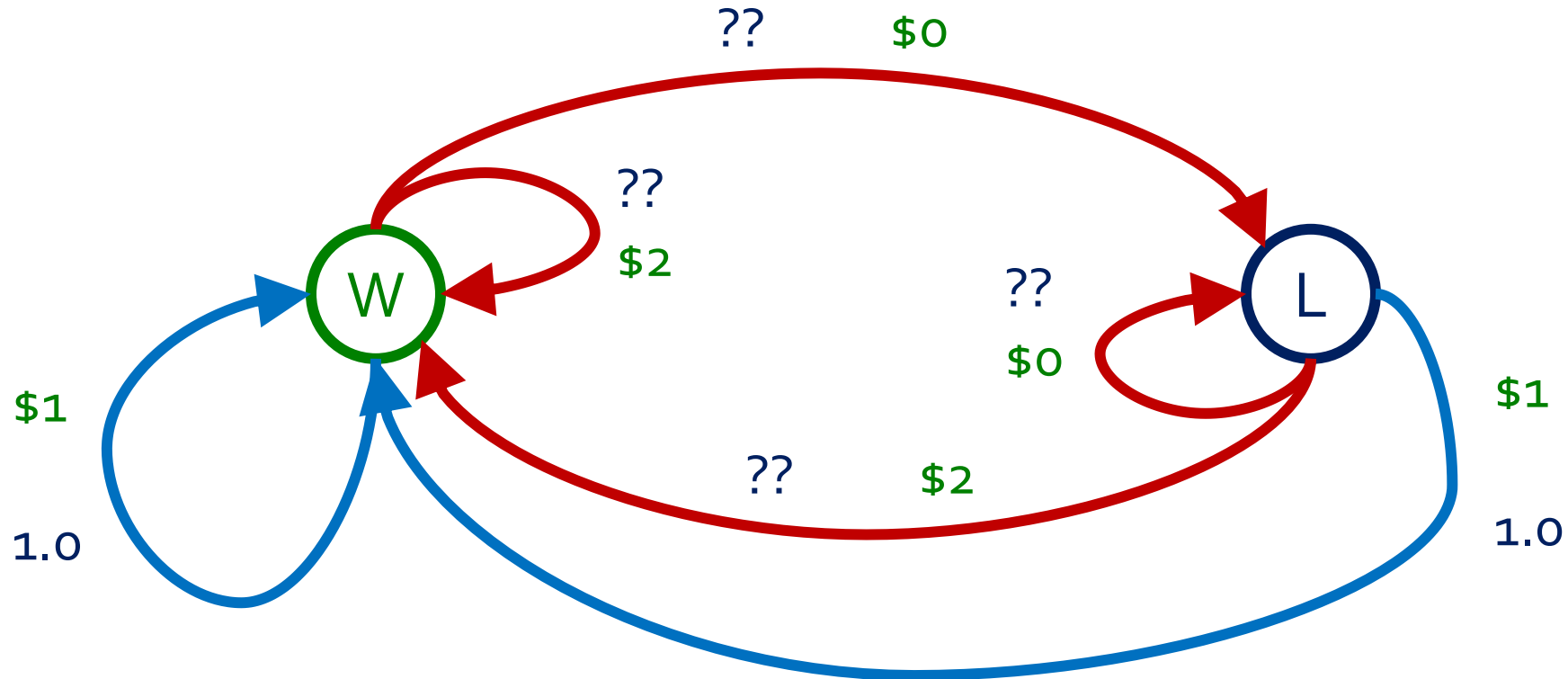
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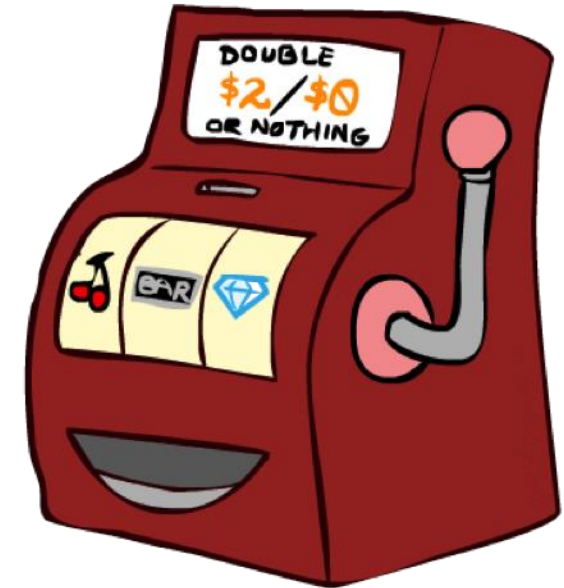


# Online Planning

- Rules changed! Red's win chance is different.



# Let's Play!



\$0 \$0 \$0 \$2 \$0  
\$2 \$0 \$0 \$0 \$0

# What Just Happened?



- That wasn't planning, it was learning!
  - Specifically, reinforcement learning
  - There was an MDP, but you couldn't solve it with just computation
  - You needed to actually act to figure it out
  
- Important ideas in reinforcement learning that came up
  - Exploration: you have to try unknown actions to get information
  - Exploitation: eventually, you have to use what you know
  - Regret: even if you learn intelligently, you make mistakes
  - Sampling: because of chance, you have to try things repeatedly
  - Difficulty: learning can be much harder than solving a known MDP

# Advanced Topics in AI

Next: Reinforcement learning



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